























Welcome to Piezo Tech!

This is a representative director, Seong-il, Yoon who takes the enormous responsibility for the company in running business.

Our piezo- tech, the word which was last 2000 a ultrasonic motor from the Republic of Korea which was unfamiliar, solely founded the company with only confidence and the belief against a technical power.

Until we've industrialized the ultrasonic motor at the domestic beginning and put out, we were in trouble. But we keep going our way.

Our piezo-tech which was feeble at first, we will be a leading company in the future.

We do our best for our future from C.E.O to all employees. With quality and technique of the best in the world, we pursue investment of positive R&D field to lead rather than the profit which is visible immediately in close at hand, and will return customer's favor. Please watch the figure we grow in the future.

C.E.O Seong-il, Yoon Piezoelectric Technology Co., Ltd.



Piezoelectric Technology histroy

2000 ~ 2005

Basic technology Development stage

2000.11	Piezoelectric Technology Co.,Ltd was established
2001.07	Certified "Venture company" (SMBA, 2001112571-6881)
2001.08	Selected " "INNO -BIZ" enterprise by SMBA of Government
2001.00	Selected living -DIZ enterprise by Sivida of Government

2001.10 Awarded the Minister's prize of Ministry of commerce, Industry and Energy, Korea for Piezoelectric Ultrasonic Motors as the very best product

2002.04	Laboratory(R&D center)established, and certified by the government
2002.12	Acquired "NT"(New Technology) mark from KITA
2003.07	Selected "Export promising enterprise" by SMBA
2004.05	Developed TULA(Tiny Ultrasonic Linear Actuator)
2004.05	Designated as "Professional enterprise in parts and material industry"
	by Ministry of Commerce, Industry and Energy.

2005.05 Acquired "QS9000" Mark (Product quality management system) from KOTRIC Selected as a accomplishment enterprise in "Korea Materials and Components in dustry developing project"

by Ministry of Commerce, Industry and Energy

2006 ~ 2010

Advanced technology and Module development stage

2006.03	Registered for "Foreign Direct Investment Company" by Woori bank (registration No:22218)
2006.06	Launched TULA50-165 Mass-production for DSC (Digital Still Camera of Samsung)
2007.04	Developed "Linear Actuator of Butterfly Type"
2007.06	Registered as a S-Partner certified supplier from Samsung Techwin (KSTW07-1061)
2007.08	Acquired a certificate of ISO9001 Quality Management System
2007.08	Acquired a certificate of ISO14001 Environmental Management Syste
2007.10	Awarded "Most Excellent Prize" with TULA in the 12th Contest of
	Excellent Development of Electronic Parts



2008.10 Acquired CE Certificate for "10W Ultrasonic Cutter" (PUC 10W)

2008.12 Selected as TULA-

"30 Excellent Successful Cases of Technology Development" by Korea Institute of Industrial Technology Evaluation and Planning

2009.09 Acquired NEP(New Excellent Product) Certification by Ministry (Ministry of Knowledge Economy NEP-MKE-2009-030)

2009.10 Launched OIS module for Hybrid DSLR camera to Samsung Electronic (Model: NX10)

2010.04 Developed AF module for barcode with INTERMEC(U.S.A) as strategic business partner

2010.08 Registered European Patent for TULA (No. EP 1,721,382B1)

2011.06 Registered Chinese Patent for TULA (No. 200580001317.6)

2012.07 Developed TULA of Rectangular type

2012.11 Won an award for exporting tower of USD 1 Million from the Korea Trade Association



TULA (Tiny Ultrasonic Linear Actuator)

TULA X X -

The diameter of piezoelectric ceramic

The length of the rod

■ FEATURES

- Very small size, light weight and simple structure
- Variable stroke
- Quick response
- Intrinsic holding force
- Excellent controllability
- Fine positioning / High resolution
- Quiet operation
- No EMI

PRODUCT LINE

TULA Series

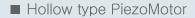
Tiny Ultrasonic Linear Actuators

- TULA 35
- TULA 50
- TULA 70

■ Butterfly Series

Butterfly typed piezoelectric Linear Motor

- · Butterfly 36
- · Butterfly 48



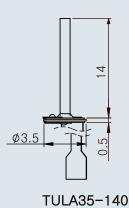
■ Mutilayer Piezo Actuator for smart device

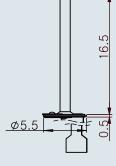
APPLICATIONS

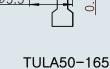
- · ZOOM, AF of camera and mobile phone
- · Optical Image Stabilizer (OIS) of camera
- · Stage module
- · ICR (infrared cut removal) of CCTV
- · Medical equipments, MEMS, Optical equipments

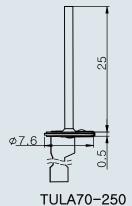


	TULA35	TULA50	TULA70
Mobile speed(mm/s)	<25	<35	<35
Max Thrust (g·f)	<20	<70	<70
Stroke (mm)	3~11	3~10	3~20
Driving voltage (V)	10~20	15~40	25~40
Driving frequency (kHz)	80~130	60~80	35~60
Current (mA)	<15	<15	<20
Power consumption (mW)	<450	<1000	<1500
Operating conditions (℃)	-10~50	-10~50	-10~50
Storage conditions (℃)	-20~80	-20~80	-20~80
Humidity (%)	15~90	15~90	15~90



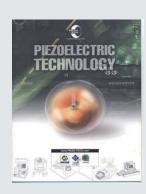








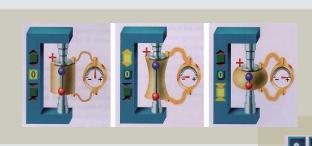




PIEZOELECTRIC ULTRASONIC MOTOR

■ PIEZOELECTRIC EFFECT

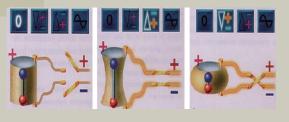
Piezoelectic effect is appearance of an electric potential across certain faces of piezoceramics when it is subjected to mechanical pressure. The word originates from the Greek word "piezein", which means "to press". A piezoelectric substance is one that produces an electric charge when a mechanical stress is applied (the substance is squeezed or stretched). Conversely, a mechanical deformation (the substance shrinks or expands) is produced when an electric field is applied.



Direct piezoelectric effect Pi = dijkTjk

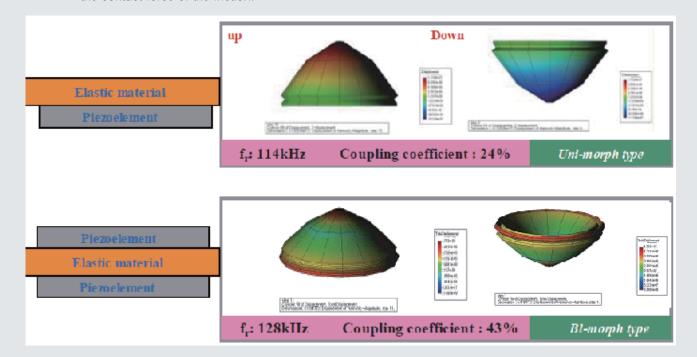


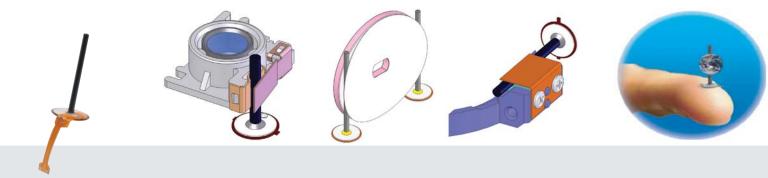
Inverse piezoelectric effect Sij = dkijEk



OPERATING PRINCIPLE

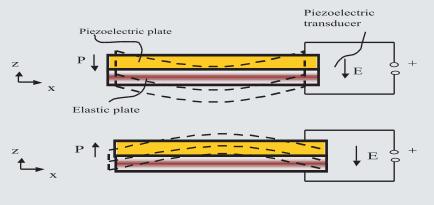
The operating principle of the TULA is explained by the characteristics of the piezoelectricity and Newton's first law. In other words, the TULA exploits the vibration modes of the piezoelectric ceramics, the inertia principle and the contact force of the friction.

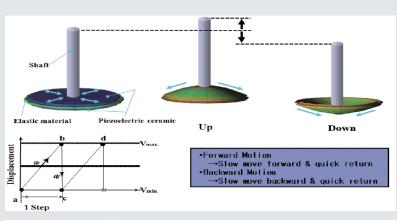


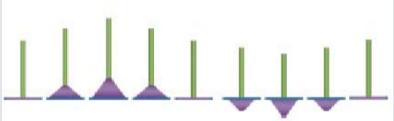


PIEZOELECTRIC ULTRASONIC MOTOR

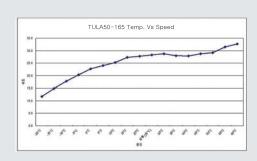
■ OPERATING PRINCIPLE

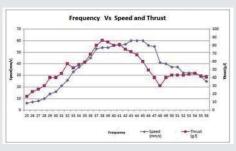


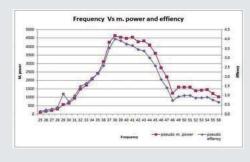




Transference of vibration















APPILICATIONS

OIS(Optical Image Stabilizer) Module

Hybrid DSLR camera

■ PT-OIS50-14



Speed: 20mm/sec Thrust Force: 20gf Stroke: 2mm

Resolution: 5µm(Hall Sensor) Power Consumption: <1000mW Size: 43mm×43mm×9.2mm

Actuator: TULA50×2 Usage: Tele Zoom Lends

■ PT-OIS50-17



Speed: 15mm/sec Thrust Force: 20gf Stroke: 2mm

Resolution: 5µm(Hall Sensor) Power Consumption: <1000mW

Size: Φ43mm×14.2mm Actuator: TULA50×2 Usage: Super Zoom Lends

AF Module

Digital camera Barcode reader Mobile phone camera

■ PT-AF50



Speed: 25mm/sec Thrust Force: 20gf

Stroke: 5mm

Resolution: 2µm(MR Sensor) Power Consumption: <400mW Size: 15.5mm×15.8mm×12mm

Actuator: TULA50×1

■ PT-OIS35



Speed: 20mm/sec Thrust Force: 20gf

Stroke: 5mm

Resolution: 2µm(MR Sensor) Power Consumption: <300mW Size: 15.5mm×15.8mm×13mm

Actuator: TULA35×1

Braille/Haptic Module



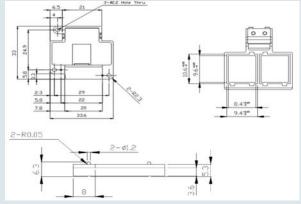
APPILICATIONS

ICR(Infrared Cut Removal) Module

IR Filter Change for day and night

■ PT-ICR50-A

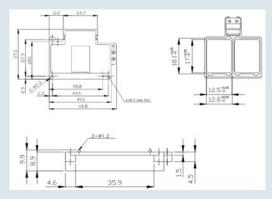




<specifications></specifications>	
Max Speed	>10mm/s
Resolution	On-Off System
Driving Frequency	70±10%kHz
Power Consumption	< 500mW
Operating Temperature	−15°C~70°C
Dimension(W×L×H)	33.6 × 33 x 5.3mm
Actuator	TULA50×1
Filter Size	10.6×9.4mm
Stroke	10.0mm

■ PT-ICR70-B

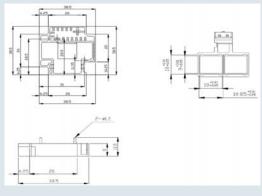




<specifications></specifications>	
Max Speed	>20mm/s
Resolution	On-Off System
Driving Frequency	50±10%kHz
Power Consumption	< 700mW
Operating Temperature	-15°C~70°C
Dimension(W×L×H)	45.1 × 37.3 x 8.9mm
Actuator	TULA70×1
Filter Size	18.1×12.8mm
Stroke	13.5mm

■ PT-ICR50-C





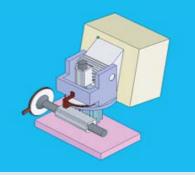
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Max Speed	>10mm/s
Resolution	On-Off System
Driving Frequency	70±10%kHz
Power Consumption	< 500mW
Operating Temperature	-15°C~70°C
Dimension(W×L×H)	38.5 × 38.5 x 11.8mm
Actuator	TULA50×1
Filter Size	10.85×10mm
Stroke	8.5mm
Remarks	Driver included

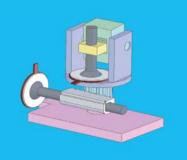
■ Filter Specification

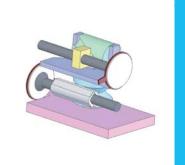
	Item	Specification Outline	Options
Dimensions	1/2 inch	$10.7 \times 10/12 \times 11$ (mm) ± 0.1	By Discussion
	1/2 inch	$7.0 \times 6.0 / 7.8 \times 7.3$ (mm) ± 0.1	by Discussion
	Qu Thickness	uartz 0.35 mm	By Discussion
		ond 15 um	by Discussion
The		Axis 45° 00' ±60'	
Composition Parts	Cut Angle Prec	ision Tolerance ±60'	By Discussion
1 di to		Rotation Angle0 ° 00' ±	
	Flatnss	Newton Ring 3 Line Max	
Transmission	Single Coatir	ng > 85% / 550 mm	
Transmission	Multi Coating	g > 90% / 450-650 mm	
Defect Limit	IR Cut Glas	s 40 µ	30 μ
Defect Limit	IR Coat	40 μ	40 µ

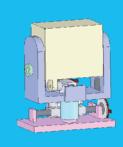


Made by TJH Corporation







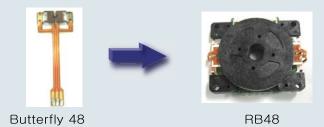


APPILICATIONS

Rotating module



<specifications></specifications>		
Rated Speed	90°/sec	
Rated Torque	100gf•cm	
0	PI (Photo Interrupter) sensor	
Sensor	(Mechanical encoder)	
Resolution	1°(180pulse/rev)	
Power Consumption	<2.5W	
Dimensions(W×L×H)	25×25×12mm	
Actuator	TULA70×1	



<specifications></specifications>	
Rated Speed	720°/sec
Rated Torque	100gf•cm
Sensor	PI (Photo Interrupter) sensor
Sensor	(Mechanical encoder)
Resolution	1°(180pulse/rev)
Power Consumption	<2.5W
Dimensions(W×L×H)	32×35.0×12mm
Actuator	Butterfly48×2

PTM(Pan & Tilt) Module

■ PT-PTM-70

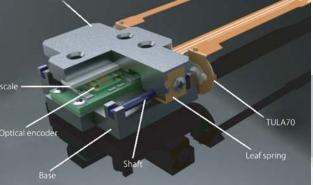


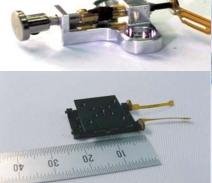
<specifications></specifications>	
Pan Angle	360°
Tilt Angle	0°~ 90°
High Speed	90°/sec
Resolution	1°(180pulse/rev)
Sensor	Photo interrupter
Power Consumption	<6W
Dimensions(Dia×H)	Ø90×127mm(Without case)
Rotating Module	RT70

■ PT-PTM-B48



<specifications></specifications>	
Pan Angle	360°
Tilt Angle	0°~ 90°
High Speed	>720°/sec
Resolution	1°(180pulse/rev)
Sensor	Photo interrupter
Power Consumption	<6W
Dimensions(Dia×H)	Ø90×127mm(Without case)
Rotating Module	RB48







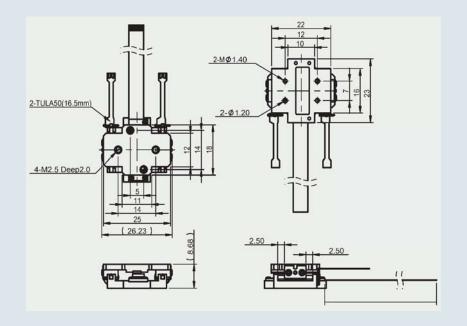
X Stage Series(Encoder type)

■ X Axis Stage(Stroke:4mm)

Model Number: XDT50-042 type

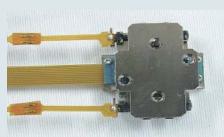


<specifications></specifications>	
Stroke	±2mm
Resolution	1µm/p(A,B Phase)
Repeatability	±3μm
Thrust	80gf
Holding Force	300gf
Moving Speed	10mm/sec
Driver	PMC-1202 type
Actuator	TULA50

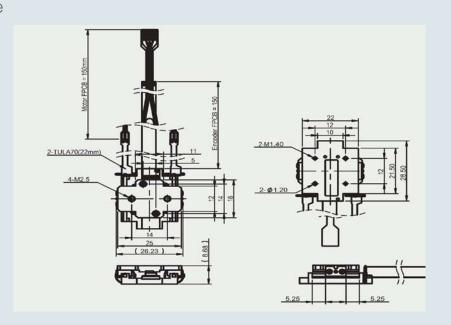


■ X Axis Stage(Stroke:10mm)

Model Number: XDT70-102 type



imm
m/p(A,B Phase)
βμm
gf
0gf
mm/sec
1C-1202 type
LA70
֡





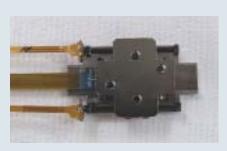




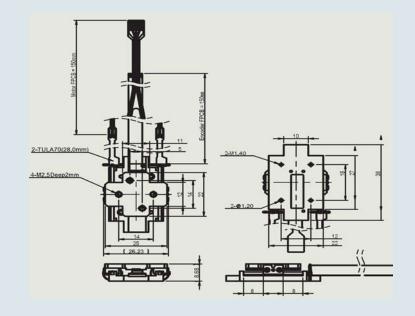


■ X Axis Stage(Stroke:15mm)

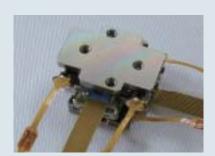
Model Number: XDT70-152 type



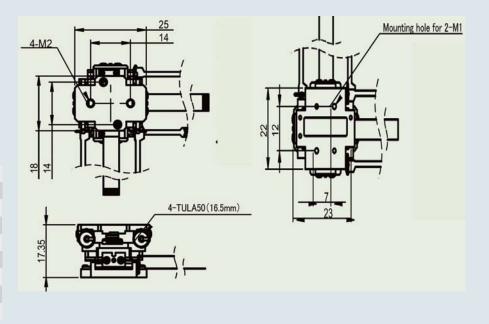
<specifications></specifications>		
Stroke	±7.5mm	
Resolution	1µm/p(A,B Phase)	
Repeatability	±3µm	
Thrust	50gf	
Holding Force	300gf	
Moving Speed	10mm/sec	
Driver	PMC-1202 type	
Actuator	TULA70	

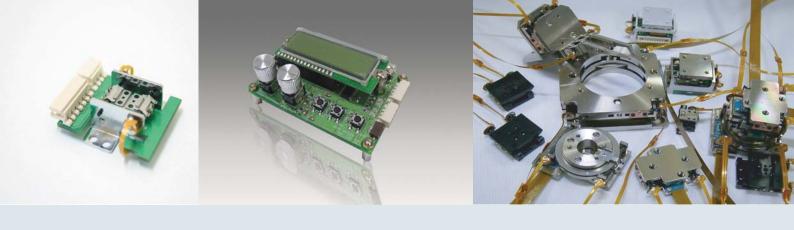


■ XY Axis Stage(Stroke:XY±2mm) Model Number: XYDT50-042 type



<specifications></specifications>	
Stroke	XY ±2mm
Resolution	1µm/p(A,B Phase)
Repeatability	±3µm
Thrust	60gf
Holding Force	250gf
Moving Speed	10mm/sec
Driver	PMC-1202 × 2
Actuator	TULA50



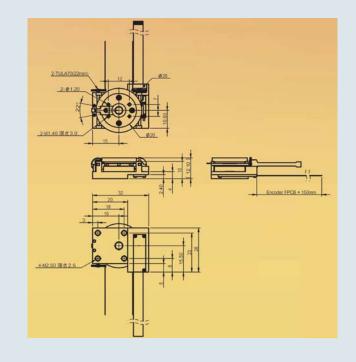


■ Theta Axis Stage

Model Number: ⊖DT70-0062 type



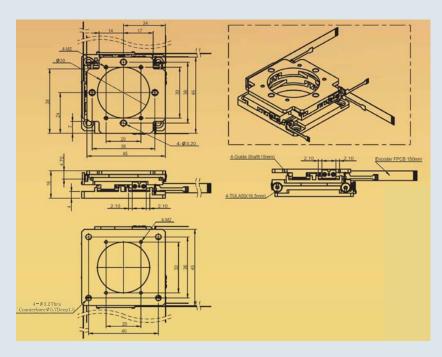
<specifications></specifications>	
Moving Angle	±3°(Customizing)
Resolution	1pulse=0.005°
Repeatability	±0.015°
Torque	50gcm
Holding Force	150gcm
Moving Speed	0.4sec/±3°
Driver	PMC-1202 type
Actuator	TULA70



■ XY Axis Hollow Stage
Model Number: XYHDT50-042 type



<specifications></specifications>	
Stroke	±2mm
Resolution	1µm/p(A,B Phase)
Repeatability	±3µm
Thrust	60gf
Holding Force	250gf
Moving Speed	10mm/sec
Driver	PMC-1202 × 2
Actuator	TULA70





TULA EV-Kit (PMC-1202 type)

The TULA EV-KIT helps the user to understand the basic characteristics of the TULA by changing the duty ratio, driving voltage and driving frequency. The purpose of the TULA EV-KIT is to assist the development of user's application with TULA.



PMC-1202



Pin Map

■ FEATURES

- 1. Contorl to TULA 35, TULA50, TULA70
- 2. Precision Position Control
 - High precision achieved with use of optical encoder
 - Open Pulse Drive
- 3. Auto Tuning
- 4. Input Command types
 - 1) External Digital Pulse Commands
 - · step/dir
 - 2) Command Input
 - · Serial over USB
 - 3) Analog Control Input (0 ~ 3.3V, Option)

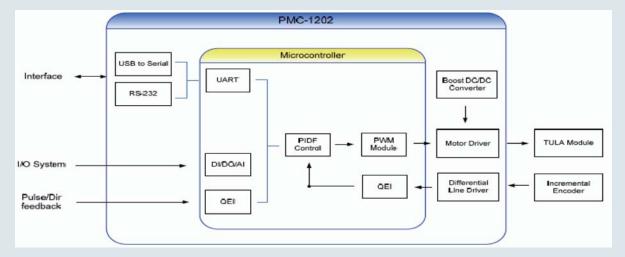
■ SPECIFICATIONS

- 1. Driving Frequency: 25 ~ 100 kHz 2. Drive Voltage: 16 ~ 35V 3. Drive Duty: 10 ~ 40%

- 4. USB Interface to PC
- 5. Supply Power: DC5V, 1A
- 6. PC Monitor Program
- 7. Size: 25*65*10(mm)

COMMUNICATION

- 1. Baud rate: 115200 bps
- 2. Transmission code: ASC II
- 3. Data length: 8 bit
- 4. Stop bit length: 1 bit
- 5. Parity check: Nil
- 6. Data classification: STX. ETX
- 7. Serial over USB / RS-232



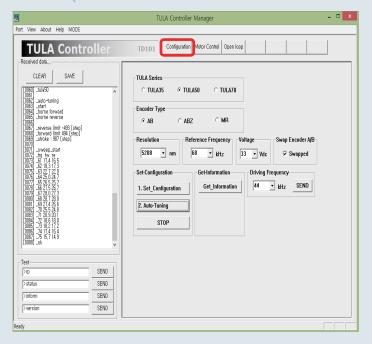
Block diagram



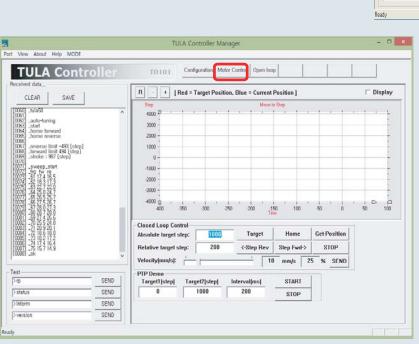




PMC-1202 PC Program



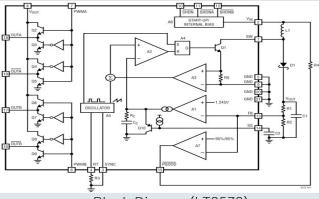
- Configuration
- 1. TULA Series select(35,50,70)
- 2. Encoder type select(AB, ABZ)
- 3. Encoder Resolution Select (0.1µm, 0.5µm, 1µm, 5µm)
- 4. Autotuning



- **TULA Controlle** Configuration Motor Control Open loop eceived data. CLEAR 20-100 Send Frequency[kHz] Duty[%] 1-48 VoltfVdcl 16-35 • Time(ms) Duration(ms/pulse) 1-6,000,000 Send Send Send Steps (Cycles) <- Reverse ⟨- Bi -⟩ SEND >rp > status SEND SEND SEND
 - Open Loop Control
 - 1. Frequency, Duty, Voltage setting
 - 2. Time/Pulse Duration select

- Closed Loop Control
- 1. Move to the absolute target position
- 2. Move to the relative target position
- 3. Reports the actual controller position
- 4. Display: During motion, the motion status can be continuously monitoring





Block Diagram(LT3572)

LT3572(Driver chip for TULA)

The Linear Technology has developed the driving IC for TULA series. Dual Full-Bridge Piezo Driver with 900mA Boost Converter

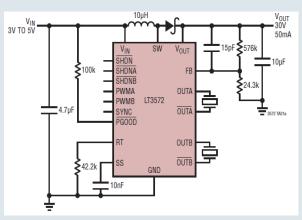
■ FEATURES

The Linear Technology has developed the driving IC for TULA series.

- 2.7V to 10V Input Voltage Range
- 900mA Boost Converter
- Dual 500mA Piezo Drivers
- Up to 180kHz PWM Frequency
- Programmable Switching Frequency from 500kHz to 2.5MHz
- Synchronizable Up to 2.5MHz
- Soft-Start

Separate Enable for Each Piezo Driver and Boost Converter

• Available in a 4mm X 4mm 20-Pin QFN Package



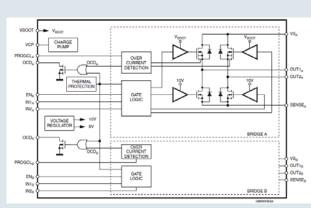
Dual Piezo Driver

L6226Q(DMOS dual full bridge driver)

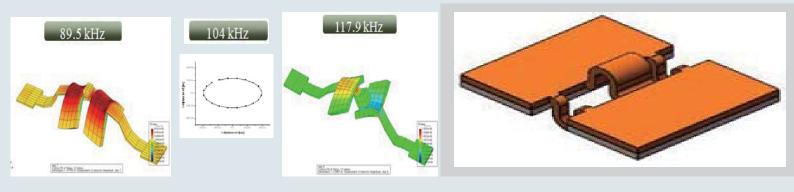
The L6226Q is a DMOS dual full bridge designed for motor control applications, realized in BCDmultipower technology, which combines isolated DMOS power transistors with CMOS and bipolar circuits on the same chip.

■ FEATURES

- Operating supply voltage from 8 to 52 V
- 2.8 A output peak current (1.4 A DC)
- RDS(on) 0.73 Ω typ. value @ TJ = 25 °C
- · Operating frequency up to 100 kHz
- Programmable high side overcurrent detection and protection
- Diagnostic output
- Paralleled operation
- Cross conduction protection
- Thermal shutdown
- · Under voltage lockout
- · Integrated fast free wheeling diodes



Block Diagram



Butterfly (Butterfly typed Piezoelectric Linear Ultrasonic Motor)

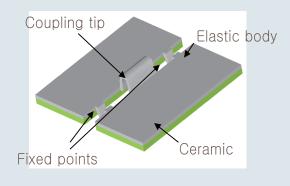
Operated by two electrical signals with 90° phase difference and the mixed mode. The moving distance of the motor can be prolonged without limit.

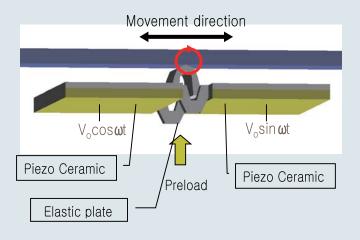




Butterfly 48

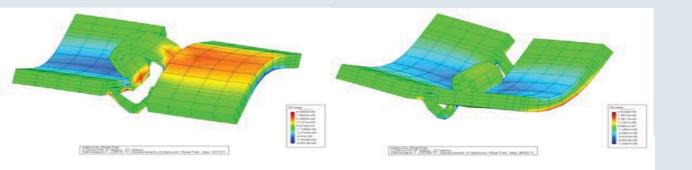
<specifications></specifications>		
	B36	B48
Max Speed	>80mm/sec	>150mm/sec
Max Thrust	>15gf	>15gf
Strke	Variable	
Driving VIItage	10~25(Bulk Ceramic)	
	3~5(Multilayer Ceramic)	
Driving Frequency	120±15kHz	80±10kHz
Power Consumption	<1.5W	<1.5W





■ APPLICATIONS

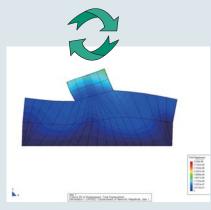
- · Micro, Nano positioning
- · Semiconductor handing system
- Precision lathe machinery, robotics for FA(Factory Automation)
- · AF camera module
- · Other driving system for industrial equipments



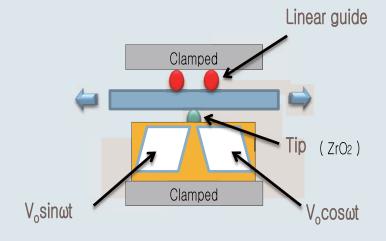


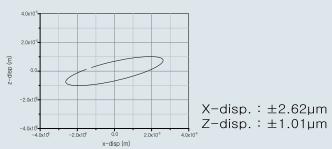
Multilayer Actuator

Multi-layer transducers with 2 electrodes Coupling tip



Deformation at 590kHz





■ PRINCIPLE

Combination of two flexural vibrations with 90 degree phase difference.

Rectangular TULA - Preliminary -



Rectangular TULA Image

<Specifications>

Type	Bi Morph	
Driving Voltage	30V	
Duty	25%	
Holding force	85gf	
Thrust force	30gf	
Speed	>13mm/sec	
Frequency	125kHz	
Dimension	$7.8 \times 2.6 \times 0.7$	

Moving Element Example





























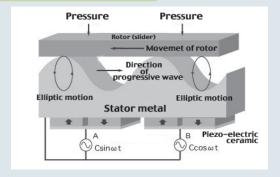


Hollow type Ultrasonic Motor

Hollow type Ultrasonic Motor

■ FEATURES

- Low speed with high torque without a gear reduction
- No heat is generated when paused with high positioning control
- · Simple, slim and lightweight design
- High responsiveness and quiet operation
- · Actuator for surveillance cameras

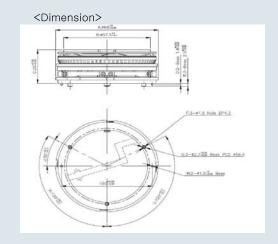


■ APPLICATION FIELD

- · Micro actuator and manipulators for medical systems, robot, camera and process engineering
- Stage for precise position controlling of semiconductor and weapon system
- · Actuators for intelligent FA, OA and HA

<Specifications>

Max Speed	≥ 30RPM		
Max Load	400gf.cm		
Driving Voltage	26.5Vdc ±5%		
Driving Frequency	27 ~ 35 kHz		
Signal Duty	50%		
Phase Difference	90 degree		
Power Consumption	≤ 1500mW		
Operating Temperature	-15°C ~ +45°C		
Storage Temperature	-30℃ ~ +70℃		



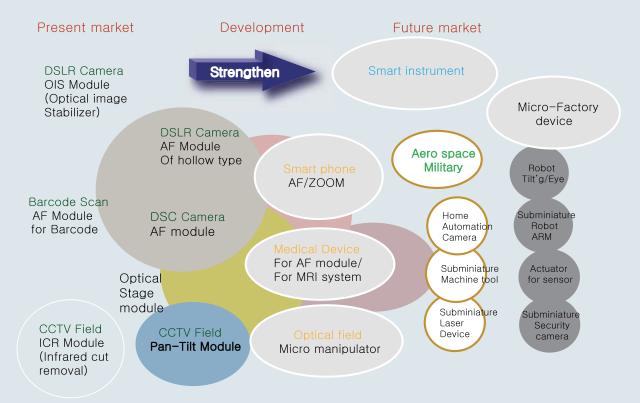
Rotary type Ultrasonic Motor

<Specifications>

	UMR40	UMR60
Shaft Dia.(mm)	Ф6	Ф8
Dimensions(mm)	44 × 44 × 19	65 × 65 × 22
Weight(g)	91	270
Drive Frequency(kHz)	34~37	40~44
Drive Voltage (Vrms)	120	120
Rated Speed(rpm)	80	100
Rated Torque(kgf • cm)	0.8	2.5
Max. Torque(kgf • cm)	>1.8	>7
Holding Toque(kgf • cm)	>2	>10
Encoder(p/r)	1,000 P/R (4,000 P/R)	
Allowable temperature rising (℃)	(On surface of the motor) 55 ℃	
Operating temperature rising (°C)	−10 ~ 50	
Storage temperature rising (℃)	− 20 ~ 60	
Life time (hrs)	3	,000

























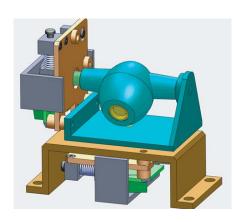






















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